

Package ‘synthesis’

July 7, 2024

Title Generate Synthetic Data from Statistical Models

Version 1.2.5

Author Ze Jiang [aut, cre] (<<https://orcid.org/0000-0002-3472-0829>>)

Maintainer Ze Jiang <ze.jiang@unsw.edu.au>

Description Generate synthetic time series from commonly used statistical models, including linear, nonlinear and chaotic systems. Applications to testing methods can be found in Jiang, Z., Sharma, A., & Johnson, F. (2019) <[doi:10.1016/j.advwatres.2019.103430](https://doi.org/10.1016/j.advwatres.2019.103430)> and Jiang, Z., Sharma, A., & Johnson, F. (2020) <[doi:10.1029/2019WR026962](https://doi.org/10.1029/2019WR026962)> associated with an open-source tool by Jiang, Z., Rashid, M. M., Johnson, F., & Sharma, A. (2020) <[doi:10.1016/j.envsoft.2020.104907](https://doi.org/10.1016/j.envsoft.2020.104907)>.

Depends R (>= 3.5.0)

License GPL (>= 3)

Encoding UTF-8

URL <https://github.com/zejiang-unsw/synthesis#readme>

BugReports <https://github.com/zejiang-unsw/synthesis/issues>

Imports stats, MASS, graphics

Suggests zoo, knitr, rmarkdown, testthat, devtools

RoxygenNote 7.2.3

VignetteBuilder knitr

NeedsCompilation no

Repository CRAN

Date/Publication 2024-07-07 15:10:02 UTC

Contents

data.gen.affine	2
data.gen.ar1	3
data.gen.ar4	4
data.gen.ar9	4

data.gen.blobs	5
data.gen.bm	6
data.gen.BUWO	7
data.gen.circles	8
data.gen.Duffing	8
data.gen.fbm	10
data.gen.fm1	11
data.gen.fm2	11
data.gen.gbm	12
data.gen.Henon	13
data.gen.HL	15
data.gen.LGSS	16
data.gen.Logistic	17
data.gen.Lorenz	18
data.gen.nl1	19
data.gen.nl2	20
data.gen.norm	21
data.gen.Rossler	22
data.gen.rw	23
data.gen.spirals	24
data.gen.SW	25
data.gen.tar	26
data.gen.tar1	27
data.gen.tar2	28
data.gen.unif	28

Index 30

data.gen.affine	<i>Generate an affine error model.</i>
-----------------	--

Description

Generate an affine error model.

Usage

```
data.gen.affine(nobs, a = 0, b = 1, ndim = 3, mu = 0, sd = 1)
```

Arguments

nobs	The data length to be generated.
a	intercept
b	slope
ndim	The number of potential predictors (default is 9).
mu	mean of error term
sd	standard deviation of error term

Value

A list of 2 elements: a vector of response (x), and a matrix of potential predictors (dp) with each column containing one potential predictor.

References

McColl, K. A., Vogelzang, J., Konings, A. G., Entekhabi, D., Piles, M., & Stoffelen, A. (2014). Extended triple collocation: Estimating errors and correlation coefficients with respect to an unknown target. *Geophysical Research Letters*, 41(17), 6229-6236. doi:10.1002/2014gl061322

Examples

```
# Affine error model from paper with 3 dummy variables
data.affine<-data.gen.affine(500)
plot.ts(cbind(data.affine$x,data.affine$dp))
```

`data.gen.ar1`*Generate predictor and response data from AR1 model.*

Description

Generate predictor and response data from AR1 model.

Usage

```
data.gen.ar1(nobs, ndim = 9)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).

Value

A list of 2 elements: a vector of response (x), and a matrix of potential predictors (dp) with each column containing one potential predictor.

Examples

```
# AR1 model from paper with 9 dummy variables
data.ar1<-data.gen.ar1(500)
plot.ts(cbind(data.ar1$x,data.ar1$dp))
```

`data.gen.ar4`*Generate predictor and response data from AR4 model.*

Description

Generate predictor and response data from AR4 model.

Usage

```
data.gen.ar4(nobs, ndim = 9)
```

Arguments

<code>nobs</code>	The data length to be generated.
<code>ndim</code>	The number of potential predictors (default is 9).

Value

A list of 2 elements: a vector of response (`x`), and a matrix of potential predictors (`dp`) with each column containing one potential predictor.

Examples

```
# AR4 model from paper with total 9 dimensions
data.ar4<-data.gen.ar4(500)
plot.ts(cbind(data.ar4$x,data.ar4$dp))
```

`data.gen.ar9`*Generate predictor and response data from AR9 model.*

Description

Generate predictor and response data from AR9 model.

Usage

```
data.gen.ar9(nobs, ndim = 9)
```

Arguments

<code>nobs</code>	The data length to be generated.
<code>ndim</code>	The number of potential predictors (default is 9).

Value

A list of 2 elements: a vector of response (x), and a matrix of potential predictors (dp) with each column containing one potential predictor.

Examples

```
# AR9 model from paper with total 9 dimensions
data.ar9<-data.gen.ar9(500)
plot.ts(cbind(data.ar9$x,data.ar9$dp))
```

data.gen.blobs	<i>Gaussian Blobs</i>
----------------	-----------------------

Description

Gaussian Blobs

Usage

```
data.gen.blobs(  
  nobs = 100,  
  features = 2,  
  centers = 3,  
  sd = 1,  
  bbox = c(-10, 10),  
  do.plot = TRUE  
)
```

Arguments

nobs	The data length to be generated.
features	Features of dataset.
centers	Either the number of centers, or a matrix of the chosen centers.
sd	The level of Gaussian noise, default 1.
bbox	The bounding box of the dataset.
do.plot	Logical value. If TRUE (default value), a plot of the generated Blobs is shown.

Details

This function generates a matrix of features creating multiclass datasets by allocating each class one or more normally-distributed clusters of points. It can control both centers and standard deviations of each cluster. For example, we want to generate a dataset of weight and height (two features) of 500 people (data length), including three groups, baby, children, and adult. Centers are the average weight and height for each group, assuming both weight and height are normally distributed (i.e. follow Gaussian distribution). The standard deviation (sd) is the sd of the Gaussian distribution while the bounding box (bbox) is the range for each generated cluster center when only the number of centers is given.

Value

A list of two variables, x and classes.

References

Amos Elberg (2018). clusteringdatasets: Datasets useful for testing clustering algorithms. R package version 0.1.1. <https://github.com/elbamos/clusteringdatasets>

Examples

```
Blobs=data.gen.blobs(nobs=1000, features=2, centers=3, sd=1, bbox=c(-10,10), do.plot=TRUE)
```

data.gen.bm

Generate a time series of Brownian motion.

Description

This function generates a time series of one dimension Brownian motion.

Usage

```
data.gen.bm(  
  x0 = 0,  
  w0 = 0,  
  time = seq(0, by = 0.01, length.out = 101),  
  do.plot = TRUE  
)
```

Arguments

x0	the start value of x, with the default value 0
w0	the start value of w, with the default value 0
time	the temporal interval at which the system will be generated. Default seq(0,by=0.01,len=101).
do.plot	a logical value. If TRUE (default value), a plot of the generated system is shown.

Value

A ts object.

References

Yanping Chen, <http://cos.name/wp-content/uploads/2008/12/stochastic-differential-equation-with-r.pdf>

Examples

```
set.seed(123)  
x <- data.gen.bm()
```

`data.gen.BUWO`*Generate build-up and wash-off model for water quality modeling*

Description

Generate build-up and wash-off model for water quality modeling

Usage

```
data.gen.BUWO(nobs, k = 0.5, a = 1, m0 = 10, q = 0)
```

Arguments

<code>nobs</code>	The data length to be generated.
<code>k</code>	build-up coefficient ($\text{kg}\cdot\text{t}^{-1}$)
<code>a</code>	wash-off rate constant (m^{-3})
<code>m0</code>	threshold at which additional mass does not accumulate on the surface (kg)
<code>q</code>	runoff ($\text{m}^3\cdot\text{t}^{-1}$)

Value

A list of 2 elements: a vector of build-up mass (x), and a vector of wash-off mass (y) per unit time.

References

Wu, X., Marshall, L., & Sharma, A. (2019). The influence of data transformations in simulating Total Suspended Solids using Bayesian inference. *Environmental modelling & software*, 121, 104493. doi:<https://doi.org/10.1016/j.envsoft.2019.104493>

Shaw, S. B., Stedinger, J. R., & Walter, M. T. (2010). Evaluating Urban Pollutant Buildup/Wash-Off Models Using a Madison, Wisconsin Catchment. *Journal of Environmental Engineering*, 136(2), 194-203. [https://doi.org/10.1061/\(ASCE\)EE.1943-7870.0000142](https://doi.org/10.1061/(ASCE)EE.1943-7870.0000142)

Examples

```
# Build up model
set.seed(101)
sample = 500
#create a gamma shape storm event
q<- seq(0,20, length.out=sample)
p <- pgamma(q, shape=9, rate =2, lower.tail = TRUE)
p <- c(p[1],p[2:sample]-p[1:(sample-1)])

data.tss<-data.gen.BUWO(sample, k=0.5, a=5, m0=10, q=p)
plot.ts(cbind(p, data.tss$x, data.tss$y), ylab=c("Q", "Build-up", "Wash-off"))
```

data.gen.circles *Circles*

Description

Circles

Usage

```
data.gen.circles(  
  n,  
  r_vec = c(1, 2),  
  start = runif(1, -1, 1),  
  s,  
  do.plot = TRUE  
)
```

Arguments

n	The data length to be generated.
r_vec	The radius of circles.
start	The center of circles.
s	The level of Gaussian noise, default 0.
do.plot	Logical value. If TRUE (default value), a plot of the generated Circles is shown.

Value

A list of two variables, x and classes.

Examples

```
Circles=data.gen.circles(n = 1000, r_vec=c(1,2), start=runif(1,-1,1), s=0.1, do.plot=TRUE)
```

data.gen.Duffing *Duffing map*

Description

Generates a 2-dimensional time series using the Duffing map.

Usage

```
data.gen.Duffing(
  nobs = 5000,
  a = 2.75,
  b = 0.2,
  start = runif(n = 2, min = -0.5, max = 0.5),
  s,
  do.plot = TRUE
)
```

Arguments

nobs	Length of the generated time series. Default: 5000 samples.
a	The a parameter. Default: 2.75.
b	The b parameter. Default: 0.2.
start	A 2-dimensional vector indicating the starting values for the x and y Duffing coordinates. Default: If the starting point is not specified, it is generated randomly.
s	The level of noise, default 0.
do.plot	Logical value. If TRUE (default value), a plot of the generated Duffing system is shown.

Details

The Duffing map is defined as follows:

$$x_n = y_{n-1}$$

$$y_n = -b \cdot x_{n-1} + a \cdot y_{n-1} - y_{n-1}^3$$

The default selection for both a and b parameters ($a=1.4$ and $b=0.3$) is known to produce a deterministic chaotic time series.

Value

A list with two vectors named x and y containing the x-components and the y-components of the Duffing map, respectively.

Note

Some initial values may lead to an unstable system that will tend to infinity.

References

Constantino A. Garcia (2019). nonlinearTseries: Nonlinear Time Series Analysis. R package version 0.2.7. <https://CRAN.R-project.org/package=nonlinearTseries>

Examples

```
Duffing.map=data.gen.Duffing(nobs = 1000, do.plot=TRUE)
```

data.gen.fbm	<i>Generate a time series of fractional Brownian motion.</i>
--------------	--

Description

This function generates a a time series of one dimension fractional Brownian motion.

Usage

```
data.gen.fbm(  
  hurst = 0.95,  
  time = seq(0, by = 0.01, length.out = 1000),  
  do.plot = TRUE  
)
```

Arguments

hurst	the hurst index, with the default value 0.95, ranging from [0,1].
time	the temporal interval at which the system will be generated. Default seq(0,by=0.01,len=1000).
do.plot	a logical value. If TRUE (default value), a plot of the generated system is shown.

Value

A ts object.

References

Zdravko Botev (2020). Fractional Brownian motion generator (<https://www.mathworks.com/matlabcentral/fileexchange/3893-fractional-brownian-motion-generator>), MATLAB Central File Exchange. Retrieved August 17, 2020.

Kroese, D. P., & Botev, Z. I. (2015). Spatial Process Simulation. In Stochastic Geometry, Spatial Statistics and Random Fields(pp. 369-404) Springer International Publishing, DOI: 10.1007/978-3-319-10064-7_12

Examples

```
set.seed(123)  
x <- data.gen.fbm()
```

data.gen.fm1	<i>Friedman with independent uniform variates</i>
--------------	---

Description

Friedman with independent uniform variates

Usage

```
data.gen.fm1(nobs, ndim = 9, noise = 1)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).
noise	The noise level in the time series.

Value

A list of 3 elements: a vector of response (x), a matrix of potential predictors (dp) with each column containing one potential predictor, and a vector of true predictor numbers.

Examples

```
###synthetic example - Friedman
#Friedman with independent uniform variates
data.fm1 <- data.gen.fm1(nobs=1000, ndim = 9, noise = 0)

#Friedman with correlated uniform variates
data.fm2 <- data.gen.fm2(nobs=1000, ndim = 9, r = 0.6, noise = 0)

plot.ts(cbind(data.fm1$x,data.fm2$x), col=c('red','blue'), main=NA, xlab=NA,
        ylab=c('Friedman with \n independent uniform variates',
              'Friedman with \n correlated uniform variates'))
```

data.gen.fm2	<i>Friedman with correlated uniform variates</i>
--------------	--

Description

Friedman with correlated uniform variates

Usage

```
data.gen.fm2(nobs, ndim = 9, r = 0.6, noise = 0)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).
r	Target Spearman correlation.
noise	The noise level in the time series.

Value

A list of 3 elements: a vector of response (x), a matrix of potential predictors (dp) with each column containing one potential predictor, and a vector of true predictor numbers.

Examples

```
###synthetic example - Friedman
#Friedman with independent uniform variates
data.fm1 <- data.gen.fm1(nobs=1000, ndim = 9, noise = 0)

#Friedman with correlated uniform variates
data.fm2 <- data.gen.fm2(nobs=1000, ndim = 9, r = 0.6, noise = 0)

plot.ts(cbind(data.fm1$x,data.fm2$x), col=c('red','blue'), main=NA, xlab=NA,
        ylab=c('Friedman with \n independent uniform variates',
              'Friedman with \n correlated uniform variates'))
```

data.gen.gbm

Generate a time series of geometric Brownian motion.

Description

This function generates a a time series of one dimension geometric Brownian motion.

Usage

```
data.gen.gbm(
  x0 = 10,
  w0 = 0,
  mu = 1,
  sigma = 0.5,
  time = seq(0, by = 0.01, length.out = 101),
  do.plot = TRUE
)
```

Arguments

<code>x0</code>	the start value of x , with the default value 10
<code>w0</code>	the start value of w , with the default value 0
<code>mu</code>	the interest/drift rate, with the default value 1.
<code>sigma</code>	the diffusion coefficient, with the default value 0.5.
<code>time</code>	the temporal interval at which the system will be generated. Default <code>seq(0,by=0.01,len=101)</code> .
<code>do.plot</code>	a logical value. If TRUE (default value), a plot of the generated system is shown.

Value

A `ts` object.

References

Yanping Chen, <http://cos.name/wp-content/uploads/2008/12/stochastic-differential-equation-with-r.pdf>

Examples

```
set.seed(123)
x <- data.gen.gbm()
```

<code>data.gen.Henon</code>	<i>Henon map</i>
-----------------------------	------------------

Description

Generates a 2-dimensional time series using the Henon map.

Usage

```
data.gen.Henon(
  nobs = 5000,
  a = 1.4,
  b = 0.3,
  start = runif(n = 2, min = -0.5, max = 0.5),
  s,
  do.plot = TRUE
)
```

Arguments

nobs	Length of the generated time series. Default: 5000 samples.
a	The a parameter. Default: 1.4.
b	The b parameter. Default: 0.3.
start	A 2-dimensional vector indicating the starting values for the x and y Henon coordinates. Default: If the starting point is not specified, it is generated randomly.
s	The level of noise, default 0.
do.plot	Logical value. If TRUE (default value), a plot of the generated Henon system is shown.

Details

The Henon map is defined as follows:

$$x_n = 1 - a \cdot x_{n-1}^2 + y_{n-1}$$

$$y_n = b \cdot x_{n-1}$$

The default selection for both a and b parameters ($a=1.4$ and $b=0.3$) is known to produce a deterministic chaotic time series.

Value

A list with two vectors named x and y containing the x -components and the y -components of the Henon map, respectively.

Note

Some initial values may lead to an unstable system that will tend to infinity.

References

Constantino A. Garcia (2019). nonlinearTseries: Nonlinear Time Series Analysis. R package version 0.2.7. <https://CRAN.R-project.org/package=nonlinearTseries>

Examples

```
Henon.map=data.gen.Henon(nobs = 1000, do.plot=TRUE)
```

data.gen.HL *Generate predictor and response data: Hysteresis Loop*

Description

Generate predictor and response data: Hysteresis Loop

Usage

```
data.gen.HL(
  nobs = 512,
  a = 0.8,
  b = 0.6,
  c = 0.2,
  m = 3,
  n = 5,
  fp = 25,
  fd,
  sd.x = 0.1,
  sd.y = 0.1
)
```

Arguments

nobs	The data length to be generated.
a	The <i>a</i> parameter. Default: 0.8.
b	The <i>b</i> parameter. Default: 0.6.
c	The <i>c</i> parameter. Default: 0.2.
m	Positive integer for the split line parameter. If m=1, split line is linear; If m is even, split line has a u shape; If m is odd and higher than 1, split line has a chair or classical shape.
n	Positive odd integer for the bulging parameter, indicates degree of outward curving (1=highest level of bulging).
fp	The frequency in the generated response. fp = 25 used in the WRR paper.
fd	A vector of frequencies for potential predictors. fd = c(3,5,10,15,25,30,55,70,95) used in the WRR paper.
sd.x	The noise level in the predictor.
sd.y	The noise level in the response.

Details

The Hysteresis is a common nonlinear phenomenon in natural systems and it can be numerical simulated by the following formulas:

$$x_t = a * \cos(2\pi i * f * t)$$

$$y_t = b * \cos(2\pi * f * t)^m - c * \sin(2\pi * f * t)^n$$

The default selection for the system parameters ($a = 0.8$, $b = 0.6$, $c = 0.2$, $m = 3$, $n = 5$) is known to generate a classical hysteresis loop.

Value

A list of 3 elements: a vector of response (x), a matrix of potential predictors (dp) with each column containing one potential predictor, and a vector of true predictor numbers.

References

LAPSHIN, R. V. 1995. Analytical model for the approximation of hysteresis loop and its application to the scanning tunneling microscope. *Review of Scientific Instruments*, 66, 4718-4730.

Examples

```
###synthetic example - Hysteresis loop
#frequency, sampled from a given range
fd <- c(3,5,10,15,25,30,55,70,95)

data.HL <- data.gen.HL(m=3,n=5,nobs=512,fp=25,fd=fd)
plot.ts(cbind(data.HL$x,data.HL$dp))
```

data.gen.LGSS

Linear Gaussian state-space model

Description

Generates data from a specific linear Gaussian state space model of the form $x_t = \phi x_{t-1} + \sigma_v v_t$ and $y_t = x_t + \sigma_e e_t$, where v_t and e_t denote independent standard Gaussian random variables, i.e. $N(0, 1)$.

Usage

```
data.gen.LGSS(
  theta,
  nobs,
  start = runif(n = 1, min = -1, max = 1),
  do.plot = TRUE
)
```

Arguments

theta	The parameters $\theta = \{\phi, \sigma_v, \sigma_e\}$ of the LGSS model.
nobs	The data length to be generated.
start	A numeric value indicating the starting value for the time series. If the starting point is not specified, it is generated randomly.
do.plot	Logical value. If TRUE (default value), a plot of the generated LGSS system is shown.

Value

A list of two variables, state and response.

References

#Dahlin, J. & Schon, T. B. 'Getting Started with Particle Metropolis-Hastings for Inference in Nonlinear Dynamical Models.' *Journal of Statistical Software, Code Snippets*, 88(2): 1–41, 2019.

Examples

```
data.LGSS <- data.gen.LGSS(theta=c(0.75,1.00,0.10), nobs=500, start=0)
```

data.gen.Logistic	<i>Logistic map</i>
-------------------	---------------------

Description

Generates a time series using the logistic map.

Usage

```
data.gen.Logistic(  
  nobs = 5000,  
  r = 4,  
  start = runif(n = 1, min = 0, max = 1),  
  s,  
  do.plot = TRUE  
)
```

Arguments

nobs	Length of the generated time series. Default: 5000 samples.
r	The r parameter. Default: 4
start	A numeric value indicating the starting value for the time series. If the starting point is not specified, it is generated randomly.
s	The level of noise, default 0.
do.plot	Logical value. If TRUE (default value), a plot of the generated Logistic system is shown.

Details

The logistic map is defined as follows:

$$x_n = r \cdot x_{n-1} \cdot (1 - x_{n-1})$$

Value

A vector of time series.

References

Constantino A. Garcia (2019). nonlinearTseries: Nonlinear Time Series Analysis. R package version 0.2.7. <https://CRAN.R-project.org/package=nonlinearTseries>

Examples

```
Logistic.map=data.gen.Logistic(nobs = 1000, do.plot=TRUE)
```

data.gen.Lorenz	<i>Lorenz system</i>
-----------------	----------------------

Description

Generates a 3-dimensional time series using the Lorenz equations.

Usage

```
data.gen.Lorenz(  
  sigma = 10,  
  beta = 8/3,  
  rho = 28,  
  start = c(-13, -14, 47),  
  time = seq(0, 50, length.out = 1000),  
  s  
)
```

Arguments

sigma	The σ parameter. Default: 10.
beta	The β parameter. Default: 8/3.
rho	The ρ parameter. Default: 28.
start	A 3-dimensional numeric vector indicating the starting point for the time series. Default: c(-13, -14, 47).
time	The temporal interval at which the system will be generated. Default: time=seq(0,50,by = 0.01).
s	The level of noise, default 0.

Details

The Lorenz system is a system of ordinary differential equations defined as:

$$\begin{aligned}\dot{x} &= \sigma(y - x) \\ \dot{y} &= \rho x - y - xz \\ \dot{z} &= -\beta z + xy\end{aligned}$$

The default selection for the system parameters ($\sigma = 10, \rho = 28, \beta = 8/3$) is known to produce a deterministic chaotic time series.

Value

A list with four vectors named *time*, *x*, *y* and *z* containing the time, the x-components, the y-components and the z-components of the Lorenz system, respectively.

Note

Some initial values may lead to an unstable system that will tend to infinity.

References

Constantino A. Garcia (2019). nonlinearTseries: Nonlinear Time Series Analysis. R package version 0.2.7. <https://CRAN.R-project.org/package=nonlinearTseries>

Examples

```
###Synthetic example - Lorenz
ts.l <- data.gen.Lorenz(sigma = 10, beta = 8/3, rho = 28, start = c(-13, -14, 47),
                      time = seq(0, by=0.05, length.out = 2000))

ts.plot(cbind(ts.l$x, ts.l$y, ts.l$z), col=c('black', 'red', 'blue'))
```

data.gen.nl1

Nonlinear system with independent/correlate covariates

Description

Nonlinear system with independent/correlate covariates

Usage

```
data.gen.nl1(nobs, ndim = 15, r = 0.6, noise = 1)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).
r	Target Spearman correlation among covariates.
noise	The noise level in the time series.

Value

A list of 3 elements: a vector of response (x), a matrix of potential predictors (dp) with each column containing one potential predictor, and a vector of true predictor numbers.

Examples

```
###synthetic example - Friedman
#Friedman with independent uniform variates
data.nl1 <- data.gen.nl1(nobs=1000)

#Friedman with correlated uniform variates
data.nl2 <- data.gen.nl2(nobs=1000)

plot.ts(cbind(data.nl1$x,data.nl2$x), col=c('red','blue'), main=NA, xlab=NA,
        ylab=c('Nonlinear system with \n independent uniform variates',
              'Nonlinear system with \n correlated uniform variates'))
```

data.gen.nl2	<i>Nonlinear system with Exogenous covariates</i>
--------------	---

Description

Nonlinear system with Exogenous covariates

Usage

```
data.gen.nl2(nobs, ndim = 7, noise = 1)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).
noise	The noise level in the time series.

Value

A list of 3 elements: a vector of response (x), a matrix of potential predictors (dp) with each column containing one potential predictor, and a vector of true predictor numbers.

References

Sharma, A., & Mehrotra, R. (2014). An information theoretic alternative to model a natural system using observational information alone. *Water Resources Research*, 50(1), 650-660.

Examples

```
###synthetic example - Friedman
#Friedman with independent uniform variates
data.nl1 <- data.gen.nl1(nobs=1000)

#Friedman with correlated uniform variates
data.nl2 <- data.gen.nl2(nobs=1000)

plot.ts(cbind(data.nl1$x,data.nl2$x), col=c('red','blue'), main=NA, xlab=NA,
        ylab=c('Nonlinear system with \n independent uniform variates',
              'Nonlinear system with \n correlated uniform variates'))
```

data.gen.norm	<i>Generate correlated normal variates</i>
---------------	--

Description

Generate correlated normal variates

Usage

```
data.gen.norm(n, mu = rep(0, 2), sd = rep(1, 2), r = 0.6, sigma)
```

Arguments

n	The data length to be generated.
mu	A vector giving the means of the variables.
sd	A vector giving the standard deviation of the variables.
r	The target Pearson correlation, default is 0.6.
sigma	A positive-definite symmetric matrix specifying the covariance matrix of the variables.

Value

A matrix of correlated normal variates

data.gen.Rossler *Rössler system*

Description

Generates a 3-dimensional time series using the Rossler equations.

Usage

```
data.gen.Rossler(
  a = 0.2,
  b = 0.2,
  w = 5.7,
  start = c(-2, -10, 0.2),
  time = seq(0, by = 0.05, length.out = 1000),
  s
)
```

Arguments

a	The <i>a</i> parameter. Default: 0.2.
b	The <i>b</i> parameter. Default: 0.2.
w	The <i>w</i> parameter. Default: 5.7.
start	A 3-dimensional numeric vector indicating the starting point for the time series. Default: c(-2, -10, 0.2).
time	The temporal interval at which the system will be generated. Default: time=seq(0,50,by=0.01) or time = seq(0,by=0.01,length.out = 1000)
s	The level of noise, default 0.

Details

The Rössler system is a system of ordinary differential equations defined as:

$$\begin{aligned}\dot{x} &= -(y + z) \\ \dot{y} &= x + a \cdot y \\ \dot{z} &= b + z * (x - w)\end{aligned}$$

The default selection for the system parameters ($a = 0.2$, $b = 0.2$, $w = 5.7$) is known to produce a deterministic chaotic time series. However, the values $a = 0.1$, $b = 0.1$, and $c = 14$ are more commonly used. These Rössler equations are simpler than those Lorenz used since only one nonlinear term appears (the product xz in the third equation).

Here, $a = b = 0.1$ and c changes. The bifurcation diagram reveals that low values of c are periodic, but quickly become chaotic as c increases. This pattern repeats itself as c increases — there are sections of periodicity interspersed with periods of chaos, and the trend is towards higher-period orbits as c increases. For example, the period one orbit only appears for values of c around 4 and is never found again in the bifurcation diagram. The same phenomenon is seen with period three; until $c = 12$, period three orbits can be found, but thereafter, they do not appear.

Value

A list with four vectors named *time*, *x*, *y* and *z* containing the time, the x-components, the y-components and the z-components of the Rössler system, respectively.

Note

Some initial values may lead to an unstable system that will tend to infinity.

References

Rössler, O. E. 1976. An equation for continuous chaos. *Physics Letters A*, 57, 397-398.

Constantino A. Garcia (2019). nonlinearTseries: Nonlinear Time Series Analysis. R package version 0.2.7. <https://CRAN.R-project.org/package=nonlinearTseries>

wikipedia <https://en.wikipedia.org/wiki/R>

Examples

```
###synthetic example - Rössler

ts.r <- data.gen.Rossler(a = 0.1, b = 0.1, w = 8.7, start = c(-2, -10, 0.2),
                        time = seq(0, by=0.05, length.out = 10000))

oldpar <- par(no.readonly = TRUE)
par(mfrow=c(1,1), ps=12, cex.lab=1.5)
plot.ts(cbind(ts.r$x,ts.r$y,ts.r$z), col=c('black','red','blue'))

par(mfrow=c(1,2), ps=12, cex.lab=1.5)
plot(ts.r$x,ts.r$y, xlab='x',ylab = 'y', type = 'l')
plot(ts.r$x,ts.r$z, xlab='x',ylab = 'z', type = 'l')
par(oldpar)
```

data.gen.rw

Generate Random walk time series.

Description

Generate Random walk time series.

Usage

```
data.gen.rw(nobs, drift = 0.2, sd = 1)
```

Arguments

nobs	the data length to be generated
drift	drift
sd	the white noise in the data

Value

A list of 2 elements: random walk and random walk with drift

References

Shumway, R. H. and D. S. Stoffer (2011). Time series regression and exploratory data analysis. Time series analysis and its applications, Springer: 47-82.

Examples

```
set.seed(154)
data.rw <- data.gen.rw(200)
plot.ts(data.rw$xd, ylim=c(-5,55), main='random walk', ylab='')
lines(data.rw$x, col=4); abline(h=0, col=4, lty=2); abline(a=0, b=.2, lty=2)
```

data.gen.spirals	<i>Spirals</i>
------------------	----------------

Description

Spirals

Usage

```
data.gen.spirals(n, cycles = 1, s = 0, do.plot = TRUE)
```

Arguments

n	The data length to be generated.
cycles	The number of cycles of spirals.
s	The level of Gaussian noise, default 0.
do.plot	Logical value. If TRUE (default value), a plot of the generated Spirals is shown.

Value

A list of two variables, x and classes.

References

Friedrich Leisch & Evgenia Dimitriadou (2010). mlbench: Machine Learning Benchmark Problems. R package version 2.1-1.

Examples

```
Spirals=data.gen.spirals(n = 2000, cycles=2, s=0.01, do.plot=TRUE)
```

data.gen.SW	<i>Generate predictor and response data: Sinusoidal model</i>
-------------	---

Description

Generate predictor and response data: Sinusoidal model

Usage

```
data.gen.SW(nobs = 500, freq = 50, A = 2, phi = pi, mu = 0, sd = 1)
```

Arguments

nobs	The data length to be generated.
freq	The frequencies in the generated response. Default freq=50.
A	The amplitude of the sinusoidal series
phi	The phase of the sinusoidal series
mu	The mean of Gaussian noise in the variable.
sd	The standard deviation of Gaussian noise in the variable.

Value

A list of time and x.

References

Shumway, R. H., & Stoffer, D. S. (2011). Characteristics of Time Series. In D. S. Stoffer (Ed.), Time series analysis and its applications (pp. 8-14). New York : Springer.

Examples

```
### Sinusoidal model
delta <- 1/12 # sampling rate, assuming monthly
period.max<- 2^5

N = 6*period.max/delta
scales<- 2^(0:5)[c(2,6)] #pick two scales
scales

### scale, period, and frequency
# freq=1/T; T=s/delta so freq = delta/s

tmp <- NULL
for(s in scales){
  tmp <- cbind(tmp, data.gen.SW(nobs=N, freq = delta/s, A = 1, phi = 0, mu=0, sd = 0)$x)
}
x <- rowSums(data.frame(tmp))
plot.ts(cbind(tmp,x), type = 'l', main=NA)
```

 data.gen.tar

 Generate a two-regime threshold autoregressive (TAR) process.

Description

Generate a two-regime threshold autoregressive (TAR) process.

Usage

```
data.gen.tar(
  nobs,
  ndim = 9,
  phi1 = c(0.6, -0.1),
  phi2 = c(-1.1, 0),
  theta = 0,
  d = 2,
  p = 2,
  noise = 0.1
)
```

Arguments

nobs	the data length to be generated
ndim	The number of potential predictors (default is 9)
phi1	the coefficient vector of the lower-regime model
phi2	the coefficient vector of the upper-regime model
theta	threshold
d	delay
p	maximum autoregressive order
noise	the white noise in the data

Details

The two-regime Threshold Autoregressive (TAR) model is given by the following formula:

$$Y_t = \phi_{1,0} + \phi_{1,1}Y_{t-1} + \dots + \phi_{1,p}Y_{t-p} + \sigma_1 e_t, \text{ if } Y_{t-d} \leq r$$

$$Y_t = \phi_{2,0} + \phi_{2,1}Y_{t-1} + \dots + \phi_{2,p}Y_{t-p} + \sigma_2 e_t, \text{ if } Y_{t-d} > r.$$

where r is the threshold and d the delay.

Value

A list of 2 elements: a vector of response (x), and a matrix of potential predictors (dp) with each column containing one potential predictor.

References

Cryer, J. D. and K.-S. Chan (2008). Time Series Analysis With Applications in R Second Edition Springer Science+ Business Media, LLC.

Examples

```
# TAR2 model from paper with total 9 dimensions
data.tar<-data.gen.tar(500)
plot.ts(cbind(data.tar$x,data.tar$dp))
```

data.gen.tar1	<i>Generate predictor and response data from TAR1 model.</i>
---------------	--

Description

Generate predictor and response data from TAR1 model.

Usage

```
data.gen.tar1(nobs, ndim = 9, noise = 0.1)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).
noise	The white noise in the data

Value

A list of 2 elements: a vector of response (x), and a matrix of potential predictors (dp) with each column containing one potential predictor.

References

Sharma, A. (2000). Seasonal to interannual rainfall probabilistic forecasts for improved water supply management: Part 1 - A strategy for system predictor identification. Journal of Hydrology, 239(1-4), 232-239.

Examples

```
# TAR1 model from paper with total 9 dimensions
data.tar1<-data.gen.tar1(500)
plot.ts(cbind(data.tar1$x,data.tar1$dp))
```

data.gen.tar2	<i>Generate predictor and response data from TAR2 model.</i>
---------------	--

Description

Generate predictor and response data from TAR2 model.

Usage

```
data.gen.tar2(nobs, ndim = 9, noise = 0.1)
```

Arguments

nobs	The data length to be generated.
ndim	The number of potential predictors (default is 9).
noise	The white noise in the data

Value

A list of 2 elements: a vector of response (x), and a matrix of potential predictors (dp) with each column containing one potential predictor.

References

Sharma, A. (2000). Seasonal to interannual rainfall probabilistic forecasts for improved water supply management: Part 1 - A strategy for system predictor identification. *Journal of Hydrology*, 239(1-4), 232-239.

Examples

```
# TAR2 model from paper with total 9 dimensions
data.tar2<-data.gen.tar2(500)
plot.ts(cbind(data.tar2$x,data.tar2$dp))
```

data.gen.unif	<i>Generate correlated uniform variates</i>
---------------	---

Description

Generate correlated uniform variates

Usage

```
data.gen.unif(n, ndim = 9, r = 0.6, sigma, method = c("pearson", "spearman"))
```

Arguments

n	The data length to be generated.
ndim	The number of potential predictors (default is 9).
r	The target correlation, default is 0.6.
sigma	A symmetric matrix of Pearson correlation, should be same as ndim.
method	The target correlation type, including Pearson and Spearman correlation.

Value

A matrix of correlated uniform variates

References

Schumann, E. (2009). Generating correlated uniform variates. COMISEF. [http://comisef.wikidot.com/tutorial: correlateduniformvariates](http://comisef.wikidot.com/tutorial:correlateduniformvariates).

Index

data.gen.affine, 2
data.gen.ar1, 3
data.gen.ar4, 4
data.gen.ar9, 4
data.gen.blobs, 5
data.gen.bm, 6
data.gen.BUWO, 7
data.gen.circles, 8
data.gen.Duffing, 8
data.gen.fbm, 10
data.gen.fm1, 11
data.gen.fm2, 11
data.gen.gbm, 12
data.gen.Henon, 13
data.gen.HL, 15
data.gen.LGSS, 16
data.gen.Logistic, 17
data.gen.Lorenz, 18
data.gen.nl1, 19
data.gen.nl2, 20
data.gen.norm, 21
data.gen.Rossler, 22
data.gen.rw, 23
data.gen.spirals, 24
data.gen.SW, 25
data.gen.tar, 26
data.gen.tar1, 27
data.gen.tar2, 28
data.gen.unif, 28